

16.7

Stokes Theorem

Review:

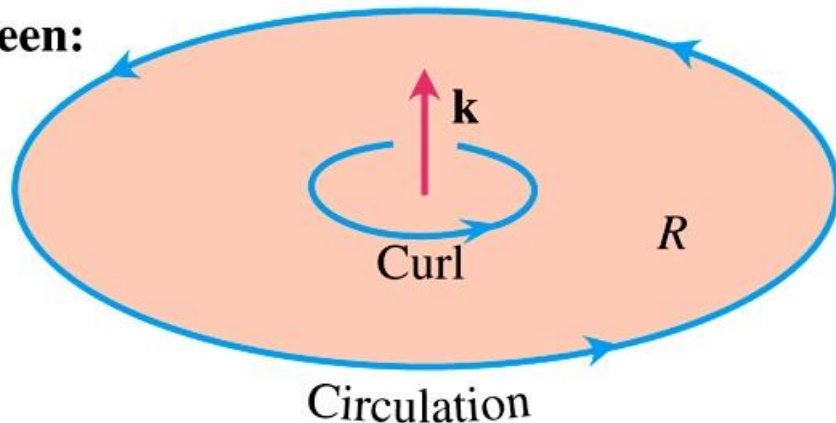
Stokes Theorem

Let S be a smooth oriented surface in \mathbf{R}^3 with a smooth closed boundary C whose orientation is consistent with that of S . Assume that $\mathbf{F} = \langle f, g, h \rangle$ is a vector field whose components have continuous first partial derivatives on S . Then

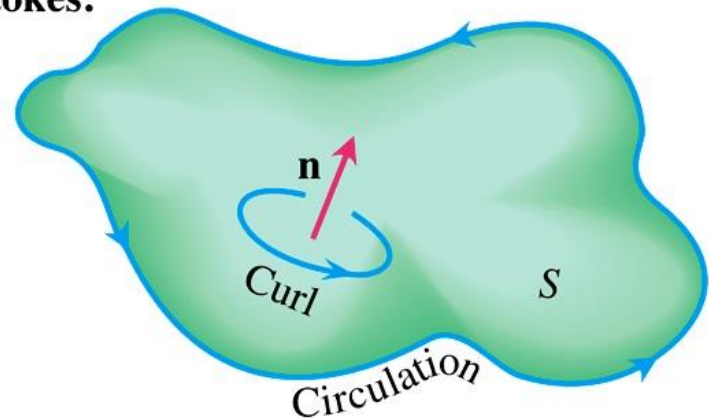
$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS,$$

where \mathbf{n} is the unit vector normal to S determined by the orientation of S .

Green:



Stokes:



Recall Green's theorem:

$$\mathbf{F} = M\mathbf{i} + N\mathbf{j} \quad \oint_C \mathbf{F} d\mathbf{r} = \oint_C Mdx + Ndy = \iint_R (N_x - M_y) dA = \iint_R (\text{curl } \mathbf{F}) \cdot \mathbf{k} dA$$

Example: Evaluate the line integral

$\oint_C \mathbf{F} \cdot d\mathbf{r}$ when $\mathbf{F} = \langle z^2, y^2, xy \rangle$, C is the triangle defined by $(1,0,0)$, $(0,1,0)$, and $(0,0,2)$, and C is traversed counter clockwise as viewed from the origin.

S : plane, we need to find the equation using a point and the normal vector to the plane

We can get the normal vector by taking the cross product of two vectors in the plane.

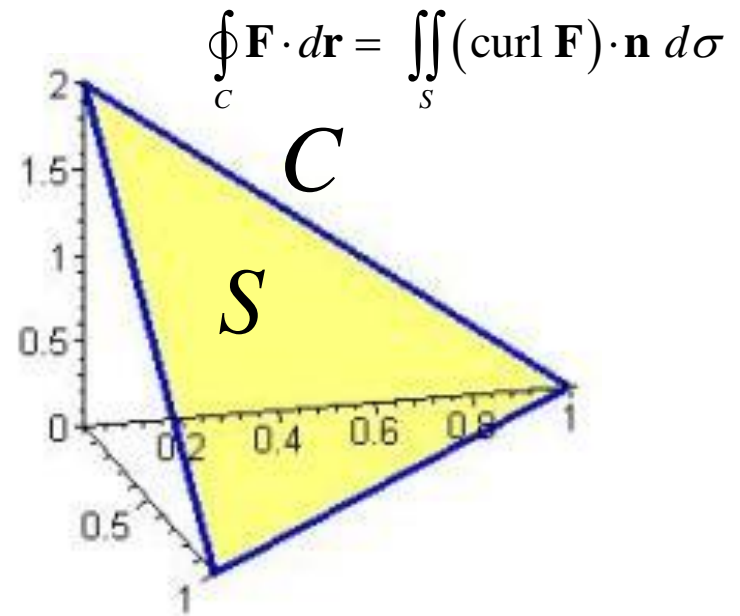
Vector from $(1,0,0)$ to $(0,1,0)$

$$v_1 = \langle 0-1, 1-0, 0-0 \rangle = \langle -1, 1, 0 \rangle$$

Vector from $(1,0,0)$ to $(0,0,2)$

$$v_2 = \langle 0-1, 0-0, 2-0 \rangle = \langle -1, 0, 2 \rangle$$

$$\mathbf{v} = v_1 \times v_2 = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -1 & 1 & 0 \\ -1 & 0 & 2 \end{vmatrix} = \langle 2, 2, 1 \rangle \quad \text{hence } \mathbf{n} = \frac{1}{3} \langle 2, 2, 1 \rangle \quad \text{wrong orientation! choose } \mathbf{n} = \frac{-1}{3} \langle 2, 2, 1 \rangle$$



$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} \, d\sigma$$

$S: 2x + 2y + z = d$ plug in any point to find d
 $(1,0,0) \rightarrow 2(1) + 2(0) + (0) = d = 2$

$$\Rightarrow 2x + 2y + z = 2 \quad \text{so } \boxed{S: z = 2 - 2x - 2y}$$

$$dS = \sqrt{1 + (z_x)^2 + (z_y)^2} \, dA$$

$$dS = \sqrt{1 + (-2)^2 + (-2)^2} \, dA$$

$$dS = 3dA$$

Example (continued): Evaluate the line integral

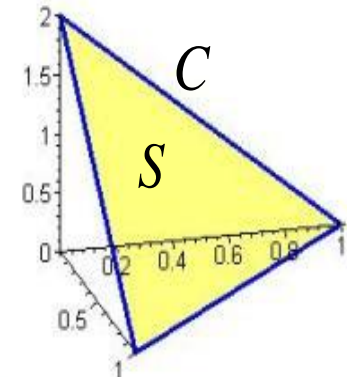
$\oint_C \mathbf{F} \cdot d\mathbf{r}$ when $\mathbf{F} = \langle z^2, y^2, xy \rangle$ and C is the

triangle defined by $(1,0,0)$, $(0,1,0)$, and $(0,0,2)$.

$$\mathbf{n} = \frac{-1}{3} \langle 2, 2, 1 \rangle$$

$$dS = 3dA$$

$$\text{plane } S : z = 2 - 2x - 2y$$



$$\text{curl } \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z^2 & y^2 & xy \end{vmatrix} = \langle x, 2z - y, 0 \rangle$$

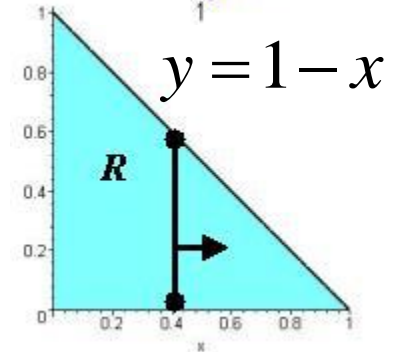
$$\iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} \, d\sigma = - \iint_R (2x + 4z - 2y) \, dA$$

$$= - \int_0^1 \int_0^{1-x} [2x + 4(2 - 2x - 2y) - 2y] \, dy \, dx$$

$$= - \int_0^1 \int_0^{1-x} [8 - 6x - 10y] \, dy \, dx = - \int_0^1 \left[(8 - 6x)y - 5y^2 \right]_0^{1-x} \, dx -$$

$$= - \int_0^1 \left[(8 - 6x)(1 - x) - 5(1 - x)^2 \right] \, dx = - \int_0^1 (x^2 - 4x + 3) \, dx$$

$$= - \left(\frac{x^3}{3} - 2x^2 + 3x \right)_0^1 = \frac{-1}{3} + 2 - 3 = \boxed{-\frac{4}{3}}$$



Example: Evaluate the flux integral $\iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} \, d\sigma$ where $\mathbf{F} = \langle 2z - y, x - z, y - x \rangle$

and S is the portion of the sphere $x^2 + y^2 + z^2 = 9$ with $z \geq y$ (a hemisphere!) and \mathbf{n} points away from the origin.

The boundary C of S is the circle obtained by intersecting the sphere with the plane $z = y$

This circle is not so easy to parametrize, so instead we write C as the boundary of a disc D in the plane $y = z$.

Using Stokes theorem twice, we get $\iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} \, d\sigma = \oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_D (\text{curl } \mathbf{F}) \cdot \mathbf{n}_2 \, d\sigma$

But now \mathbf{n}_2 is the normal to the disc D , i.e. to the plane $y = z$: $\mathbf{n}_2 = \frac{1}{\sqrt{2}} \langle 0, -1, +1 \rangle$ (check orientation!)

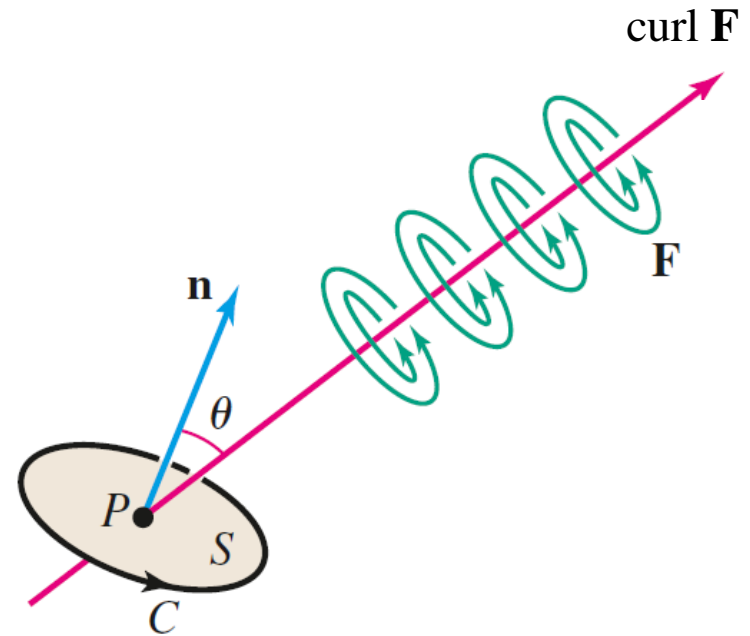
$$\text{curl } \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2z - y & x - z & y - x \end{vmatrix} = 2\mathbf{i} + 3\mathbf{j} + 2\mathbf{k} \quad \text{curl } \mathbf{F} \cdot \mathbf{n}_2 = \frac{-1}{\sqrt{2}}$$

$$\iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n}_2 \, d\sigma = \iint_D \frac{-1}{\sqrt{2}} \, d\sigma = \frac{-1}{\sqrt{2}} \text{area}(D) = \frac{-1}{\sqrt{2}} \pi 3^2 = \boxed{\frac{-9}{\sqrt{2}} \pi}$$

Application of Stokes
$$\iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{n} \, dS = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

Fix a point P and let \mathbf{n} be a vector at P

Let S be a disc of radius r in a plane orthogonal to \mathbf{n} and centered at P



For small r , the left hand side is approximately

$$(\text{curl } \mathbf{F})_P \cdot \mathbf{n} \times \iint_S 1 \cdot d\sigma = (\text{curl } \mathbf{F})_P \cdot \mathbf{n} \times \text{area}(S) = (\text{curl } \mathbf{F})_P \cdot \mathbf{n} \times (\pi r^2)$$

Thus
$$(\text{curl } \mathbf{F})_P \cdot \mathbf{n} \approx \frac{1}{\pi r^2} \oint_C \mathbf{F} \cdot d\mathbf{r}$$

as r goes to 0 we get:

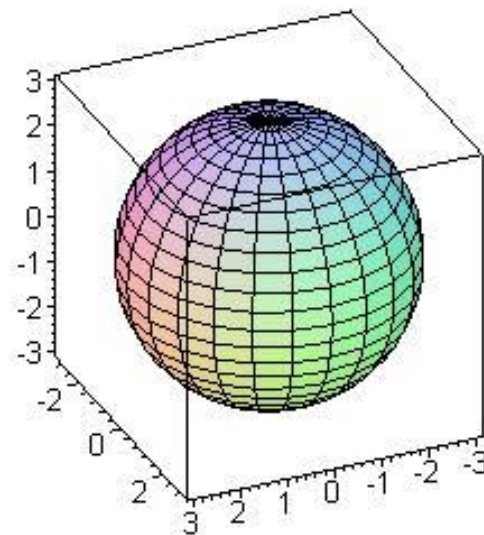
$$(\text{curl } \mathbf{F})_P \cdot \mathbf{n} = \lim_{r \rightarrow 0} \frac{1}{\pi r^2} \oint_C \mathbf{F} \cdot d\mathbf{r}$$

16.8

Divergence Theorem

Divergence Theorem

- D : a closed and bounded region in 3-space
- S : the piecewise smooth boundary of D
- \mathbf{n} : the unit normal to S , pointing outward
- \mathbf{F} : $\mathbf{F} = \langle P, Q, R \rangle$ is a vector field with P, Q, R , and all first partial derivatives continuous in the region in D



$$\iint_S (\mathbf{F} \cdot \mathbf{n}) \, d\sigma = \iiint_D \operatorname{div} \mathbf{F} \, dV$$

total outward flux through the surface S = integral of local flux over the interior

Compare with flux version of Green's theorem for $\mathbf{F} = M\mathbf{i} + N\mathbf{j}$

$$\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \oint_C -N \, dx + M \, dy = \iint_R (M_x + N_y) \, dA \quad \text{or} \quad \oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \iint_R \operatorname{div}(\mathbf{F}) \, d\sigma$$

Example: Let S be the surface of the cube $D: 0 \leq x \leq 1, 0 \leq y \leq 1, 0 \leq z \leq 1$

and $\mathbf{F} = (e^x + z)\mathbf{i} + (y^2 - x)\mathbf{j} + (-xe^y)\mathbf{k}$.

Compute the outward flux $\iint_S (\mathbf{F} \cdot \mathbf{n}) d\sigma$

$$\begin{aligned}\iint_S (\mathbf{F} \cdot \mathbf{n}) d\sigma &= \iiint_D \operatorname{div} \mathbf{F} dV \\ &= \iiint_D (e^x + 2y) dV \\ &= \int_0^1 \int_0^1 \int_0^1 (e^x + 2y) dx dy dz \\ &= \int_0^1 \int_0^1 \int_0^1 e^x dx dy dz + \int_0^1 \int_0^1 \int_0^1 2y dx dy dz \\ &= e^x \Big|_0^1 + y^2 \Big|_0^1 = e - 1 + 1 = e\end{aligned}$$

Example: Use the divergence theorem to find the outward flux $\iint_S (\mathbf{F} \cdot \mathbf{n}) d\sigma$

of the vector field $\mathbf{F} = x^3\mathbf{i} + y^3\mathbf{j} + z^3\mathbf{k}$ with D the region bounded by the sphere $x^2 + y^2 + z^2 = a^2$.

$$\begin{aligned}\iint_S (\mathbf{F} \cdot \mathbf{n}) d\sigma &= \iiint_D \operatorname{div} \mathbf{F} dV \\ &= \iiint_D (3x^2 + 3y^2 + 3z^2) dV \\ &= \int_0^{2\pi} \int_0^{\pi} \int_0^a (3\rho^2) \rho^2 \sin \phi d\rho d\phi d\theta \\ &= \int_0^{2\pi} \int_0^{\pi} \left[\frac{3}{5} \rho^5 \right]_0^a \sin \phi d\phi d\theta \\ &= \frac{3}{5} a^5 \int_0^{2\pi} \int_0^{\pi} \sin \phi d\phi d\theta \\ &= \frac{3}{5} a^5 \int_0^{2\pi} [-\cos \phi]_0^{\pi} d\theta = \frac{6}{5} a^5 \int_0^{2\pi} d\theta = \boxed{\frac{12\pi}{5} a^5}\end{aligned}$$

