

*Asymptotically Truthful Equilibrium Selection
in Large Congestion Games*

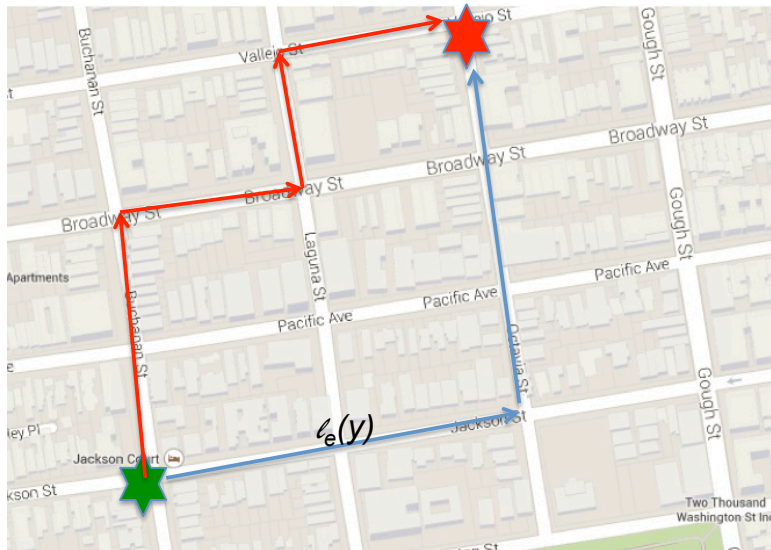
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Related Work

- **Large Games**
 - Roberts and Postlewaite 1976
 - Immorlica and Mahdian 2005, Kojima and Pathak 2009, Kojima et al 2010
 - Bodoh-Creed 2013
 - Azevedo and Budish 2011
- **Incorporating a Mediator**
 - Monderer and Tennenholtz 2003, 2009
 - Ashlagi et al 2009
- **Work most closely related to ours**
 - Kearns et al 2014.

Routing Game



Routing Game

- A game \mathcal{G} is defined by
 - A set of n players
 - A set of types $\mathcal{U} \implies$ **source destination** pair $s_i \in \mathcal{U}$.
 - A set of actions $A \implies$ **routes** for each source destination pair.
 - A cost function $c : \mathcal{U} \times A^n \rightarrow \mathbb{R}$

$$c(s_i, \mathbf{a}) = \sum_{e \in a_i} \ell_e(y_e(\mathbf{a}))$$

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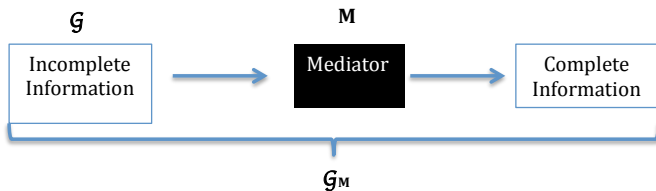
- Players may not know each others type.
 - n may be HUGE!!
 - Types may be sensitive information
- **Main Goal** : Have players play a pure strategy Nash equilibrium of the complete information game in settings of partial information.

Mediator for a Routing Game

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Introduce a Mediator



- A mediator is an algorithm $M : (\mathcal{U} \cup \perp)^n \rightarrow (A \cup \perp)^n$.

Weak Mediator



Weak Mediator



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Weak Mediator



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Weak Mediator



- Mediator cannot force people to use it
- Players need not follow its suggested action
- Players may lie to the mechanism if they choose to use it.

Augmented Game

- Define the augmented game \mathcal{G}_M (Kearns et al 2014):
 - Action Space:

$$A' = \{(s, f) : s \in \mathcal{U} \cup \perp, f : (A \cup \perp) \rightarrow A\}$$

$$g_i = (s_i, f_i) \in A'$$

- Costs for $\mathbf{g}' = ((s'_i, f_i))_{i=1}^n$:

$$c_M(s_i, \mathbf{g}') = \mathbb{E}_{\mathbf{a} \sim M(\mathbf{s}')} [c(s_i, \mathbf{f}(\mathbf{a}))]$$

Good Behavior



- Player's should:

Good Behavior



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Good Behavior



- Player's should:
 - Use the Mediator M
 - Report her true type to M
 - Follow the suggested action of $M \implies f_i = \text{identity map.}$

Joint Differential Privacy

- (Kearns et al 2014) Let $M : D^n \rightarrow O^n$. Then M satisfies ϵ -joint differential privacy if for every $\mathbf{s} \in D^n$, for every $i \in [n]$, $s'_i \in D$ and for every $B \subset O^{n-1}$

$$\mathbb{P}[M(\mathbf{s})_{-i} \in B] \leq e^\epsilon \mathbb{P}[M(s'_i, \mathbf{s}_{-i})_{-i} \in B]$$

Billboard Lemma



Billboard Lemma



- If a mechanism $M : \mathcal{U}^n \rightarrow \mathcal{O}$ is (ϵ, δ) -differentially private and consider any function $\phi : \mathcal{U} \times \mathcal{O} \rightarrow \mathcal{A}^n$. Define $M' : \mathcal{U}^n \rightarrow \mathcal{A}^n$ to be

$$M'(\mathbf{s})_i = \phi(s_i, M(\mathbf{s})).$$

Then M' is (ϵ, δ) - joint differentially private.

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Motivating Theorem

- Let \mathcal{G} be any game with costs in $[0, m]$, and let M be a mediator such that
 - It is ϵ -joint differentially private
 - For any set of reported types \mathbf{s} , it outputs an η -approximate pure strategy Nash Equilibrium.
- Then good behavior \mathbf{g}^* is an η' -approximate ex-post equilibrium for the incomplete information game \mathcal{G}_M where

$$\eta' = 2m\epsilon + \eta$$

Main Theorem

- There *exists* such a mechanism from the motivating theorem for **large** congestion games.
- Further, we show that good behavior \mathbf{g}^* is an η' -approximate ex-post equilibrium for the incomplete information game \mathcal{G}_M where

$$\eta' = \tilde{O} \left(\left(\frac{m^5}{n} \right)^{1/4} \right) \rightarrow 0 \text{ as } n \rightarrow \infty$$

Large Games



Large Games

- We assume that each player cannot significantly change the cost of another player by changing her route.

$$|\ell_e(y_e) - \ell_e(y_e + 1)| \leq \frac{1}{n} \quad \text{for } y_e \in [n] \text{ and } e \in E.$$

- The costs then satisfy for $j \neq i$ and $a'_j \neq a_j \in A$

$$|c(s_i, (a_j, \mathbf{a}_{-j})) - c(s_i, (a'_j, \mathbf{a}_{-j}))| \leq \frac{m}{n}.$$

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- Limit the number of times a single player can change routes.

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- In congestion games, allowing each player to best respond given the other players routes will converge to an approximate Nash Equilibrium.
- We will have an algorithm that will have each player move if she can improve her cost by more than α : **α -Best Response**
- There can be no more than $T = \frac{mn}{\alpha}$ best responses.
- We need to only maintain a count of the number of people on every edge to compute α -Best Responses for each player

Binary Mechanism

- Chan et al 2011 and Dwork et al 2010 give a way to obtain an online count of a sensitivity 1 stream $\omega \in \{0,1\}^T$ such that the output \hat{y}^t for any $t = 1, 2, \dots, T$ is
 - ϵ differentially private
 - Has high accuracy to the exact count y^t for every $t = 1, \dots, T$

$$|\hat{y}^t - y^t| \leq \tilde{O}\left(\frac{1}{\epsilon}\right)$$

0	1	1	0	1	1	0	0		47		1	0	1
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Generalized Binary Mechanism

0	-1	1	-1	0	0	1	1		21		1	0	-1
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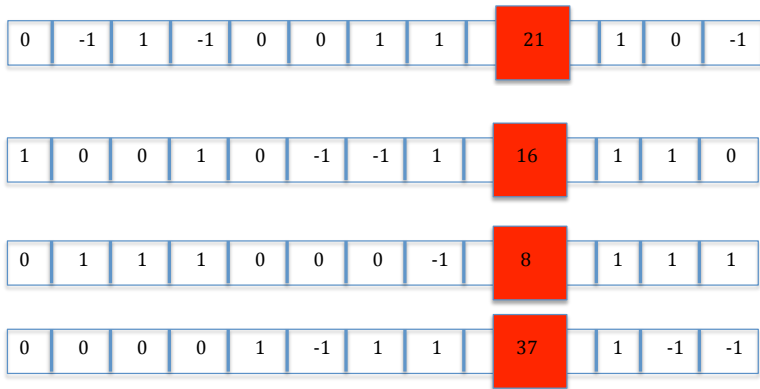
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1	0	0	1	0	-1	-1	1		16		1	1	0
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0	1	1	1	0	0	0	-1		8		1	1	1
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0	0	0	0	1	-1	1	1		37		1	-1	-1
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Generalized Binary Mechanism



- Each of the m streams are k -sensitive, so we get
 - ϵ differentially private counters
 - With high probability

$$|\hat{y}_e^t - y_e^t| \leq \tilde{O}\left(\frac{km}{\epsilon}\right) \forall e \in E, t = 1, \dots, T$$

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- All the players can only make $T = \tilde{\mathcal{O}}\left(\frac{mn}{\alpha}\right)$ (with high probability).
- A player only changes routes k times

$$k = \mathcal{O}\left(\frac{m^2}{\alpha^2}\right)$$

Equilibrium Analysis of our Algorithm

- With high probability, after $T = \tilde{O}\left(\frac{mn}{\alpha}\right)$ moves by all players, no player will be able to improve her *private* cost by more than α . If we set

$$\alpha = \tilde{\Theta}\left(\left(\frac{m^4}{n\epsilon}\right)^{1/3}\right)$$

then we know no player will be able to improve her *actual* cost by more than

$$\eta \leq \alpha + \text{Error from BM} = \tilde{O}\left(\left(\frac{m^4}{n\epsilon}\right)^{1/3}\right)$$

Equilibrium Analysis of our Algorithm

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- Is it Joint Differentially Private?
- Recall our motivating theorem that says *good* behavior is an η' -approximate ex-post equilibrium for \mathcal{G}_M and we can set ϵ (which is a parameter we control) to satisfy the following

$$\eta' = \tilde{O} \left(\left(\frac{m^5}{n} \right)^{1/4} \right) \rightarrow 0 \quad \text{as} \quad n \rightarrow \infty$$

Open Questions

- Can Nash Equilibria of the complete information game be implemented as exact ex-post or Bayes Nash Equilibria of the incomplete information game?
- Does there exist a jointly differentially private algorithm for computing approximate Nash Equilibria for *general* large games?