Math 240: Spring/Mass Systems II

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Monday, March 26, 2012

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2 Spring/Mass Systems with Damped Motion

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- Learn how to model spring/mass systems with damped motion.
- Learn how to model spring/mass systems with driven motion.

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Spring/Mass Systems with Damped Motion

Undamped motion is unrealistic. Instead assume we have a damping force proportional to the instantaneous velocity.

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$$\frac{d^2x}{dt^2} + \frac{\beta}{m}\frac{dx}{dt} + \frac{k}{m}x = 0$$

is now our model, where *m* is the mass, *k* is the spring constant, β is the damping constant and x(t) is the position of the mass at time *t*.

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Changing Variables

Let

$$2\lambda = rac{eta}{m}$$
 and $\omega^2 = rac{k}{m}$.

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and the roots of the Aux. Equation become

$$m_1 = -\lambda + \sqrt{\lambda^2 - \omega^2}$$
 and $m_2 = -\lambda - \sqrt{\lambda^2 - \omega^2}$

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Case 1: Overdamped

If $\lambda^2 - \omega^2 > 0$ the system is **overdamped** since β is large when compared to k. In this case the solution is

$$x = e^{-\lambda t} (c_1 e^{\sqrt{\lambda^2 - \omega^2}t} + c_2 e^{\sqrt{\lambda^2 - \omega^2}t}).$$

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Case 2: Critically Damped

If $\lambda^2 - \omega^2 = 0$ the system is **critically damped** since a slight decrease in the damping force would result in oscillatory motion. In this case the solution is

$$x = e^{-\lambda t} (c_1 + c_2 t)$$

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Case 3: Underdamped

If $\lambda^2 - \omega^2 < 0$ the system is **underdamped** since k is large when compared to β . In this case the solution is

$$x = e^{-\lambda t}(c_1 cos(\sqrt{\omega^2 - \lambda^2}t) + c_2 sin(\sqrt{\omega^2 - \lambda^2}t))$$

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A 4 meter spring measures 8 meters long after a force of 16 newtons acts to it. A mass of 8 kilograms is attached to the spring. The medium through which the mass moves offers a damping force equal to $\sqrt{2}$ times the instantaneous velocity. Find the equation of motion if the mass is initially released from the equilibrium position with a downward velocity of 5 meters/sec.

Driven Motion

When an external force f(t) acts on the mass on a spring, the equation for our model of motion becomes

$$\frac{d^2x}{dt^2} = -\frac{\beta}{m}\frac{dx}{dt} - \frac{k}{m}x + \frac{f(t)}{m}$$

Driven Motion

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$$\frac{d^2x}{dt^2} = -\frac{\beta}{m}\frac{dx}{dt} - \frac{k}{m}x + \frac{f(t)}{m}$$

or in the language of λ and ω ,

$$\frac{d^2x}{dt^2} + 2\lambda \frac{dx}{dt} + \omega^2 x = \frac{f(t)}{m}$$

When a mass of 2 kg is attached to a spring whose constant is 32 N/m, it comes to rest at equilibrium position. Starting at t = 0 a force of $f(t) = 65e^{-2t}$ is applied to the system. In the absence of damping, find the equation of motion.

When a mass of 2 kg is attached to a spring whose constant is 32 N/m, it comes to rest at equilibrium position. Starting at t = 0 a force of $f(t) = 65e^{-2t}$ is applied to the system. In the absence of damping, find the equation of motion.

What is the amplitude of the oscillation after a very long time?

Transient and Steady State terms

Definition

In some cases, the solution to a D.E. can be written as the sum of a periodic function, $x_p(t)$, and a function that tends to zero as t tends to infinity, $x_c(t)$. In these cases, we say $x_p(t)$ is the **steady state term** and $x_c(t)$ is the **transient term**.