Math 240: Linear Differential Equations

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2 Solutions to homogeneous equations

- Solutions to nonhomogeneous equations
- 4 Solutions to constant coefficient homogeneous equations

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Understand the form of solutions to the following types of higher order, linear differential equations

- Initial Value Problems
- Item Bound State And Monhomogeneous Equations.

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Solutions as a subspace

Theorem

(The Superposition Principle) The set of solutions to an nth-order homogeneous differential equation on an interval I form an n-dimensional vector subspace of $C^n(I)$. A basis for this space is called a **fundamental set**.

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General Solutions to Nonhomogeneous Linear D.E.s

Theorem

Let y_p be any particular solution of the nonhomogeneous linear nth-order differential equation on an interval I. Let $y_1, y_2, ..., y_n$ be a fundamental set of solutions to the associated homogeneous differential equation. Then the general solution to the nonhomogeneous equation on the interval is

$$y = c_1 y_1(x) + c_2 y_2(x) + ... + c_n y_n(x) + y_p$$

where the c_i are arbitrary constants.

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Our goal is to solve **constant coefficient** linear homogeneous differential equations.

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What if we guess $y = e^{mx}$ as a solution to y'' + y' - 6y = 0?

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In this case, we get $e^{mx}(am^2 + bm + c) = 0$. There are three possibilities for the roots of a quadratic equation.

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Case 1: Distinct Roots

If $am^2 + bm + c$ has distinct roots m_1 and m_2 , then the general solution to ay'' + by' + cy = 0 is

$$y = c_1 e^{m_1 x} + c_2 e^{m_2 x}$$

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Case 2: Repeated Roots

If $am^2 + bm + c$ has a repeated root m_1 , then the general solution to ay'' + by' + cy = 0 is

$$y = c_1 e^{m_1 x} + c_2 x e^{m_1 x}$$

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Case 3: Complex Roots

If $am^2 + bm + c$ has complex roots $m_1 = \alpha + i\beta$ and $m_2 = \alpha - i\beta$, then the general solution to ay'' + by' + cy = 0 is

$$y = c_1 e^{\alpha x} \cos(\beta x) + c_2 e^{\alpha x} \sin(\beta x)$$

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Auxiliary Equations

Given a linear homogeneous constant-coefficient differential equation

$$a_n \frac{d^n y}{dx^n} + a_{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots a_1 \frac{dy}{dx} + a_0 y = 0,$$

the Auxiliary Equation is

$$a_n m^n + a_{n-1} m^{n-1} + \dots a_1 m + a_0 = 0.$$

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Auxiliary Equations

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$$a_n \frac{d^n y}{dx^n} + a_{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots a_1 \frac{dy}{dx} + a_0 y = 0,$$

the Auxiliary Equation is

$$a_n m^n + a_{n-1} m^{n-1} + \dots a_1 m + a_0 = 0.$$

The Auxiliary Equation determines the general solution.

Solutions to constant coefficient homogeneous equations

General Solution from the Auxiliary Equation

• If *m* is a real root of the auxiliary equation of multiplicity *k* then e^{mx} , xe^{mx} , x^2e^{mx} , ..., $x^{k-1}e^{mx}$ are linearly independent solutions.

General Solution from the Auxiliary Equation

- If *m* is a real root of the auxiliary equation of multiplicity *k* then e^{mx} , xe^{mx} , x^2e^{mx} , ..., $x^{k-1}e^{mx}$ are linearly independent solutions.
- If (α + iβ) and (α + iβ) are a roots of the auxiliary equation of multiplicity k then
 e^{αx} cos(βx), xe^{αx} cos(βx), ..., x^{k-1}e^{αx} cos(βx) and
 e^{αx} sin(βx), xe^{αx} sin(βx), ..., x^{k-1}e^{αx} sin(βx) are linearly independent solutions.