Math 240: Systems of Differential Equations

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Friday November 16, 2012

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Combine linear algebra and differential equations to study systems of differential equations.

Solve linear systems of differential equations using Eigenvalues.

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If $A \in M_n(\mathbb{R})$

Given a constant coefficient, linear, homogeneous, first-order system

our intuition prompts us to guess a solution vector of the form

$$\mathbf{x} = \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{pmatrix} e^{\lambda t} = \mathbf{K} e^{\lambda t}$$

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Hence, we can find such a solution vector iff K is an eigenvector for A with eigenvalue λ .

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General Solution with Distinct Real Eigenvalues

Theorem

Let $A \in M_n(\mathbb{R})$. If A has n linearly independent eigenvectors $v_1, v_2, ..., v_n$, with **real** eigenvalues $\lambda_1, \lambda_2, ..., \lambda_n$ (not necessarily distinct), then the general solution to $\mathbf{x'}=\mathbf{A}\mathbf{x}$ on any interval is

$$\mathbf{X} = c_1 v_1 e^{\lambda_1 t} + c_2 v_2 e^{\lambda_2 t} + \dots + c_n v_n e^{\lambda_n t}$$

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Exercise: Solve the linear system X' = AX if

$$A = \left(\begin{array}{rr} -1 & 2\\ -7 & 8 \end{array}\right)$$

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Complex Eigenvalues

Theorem

Let $\lambda = a + bi$ be a **complex** eigenvalue of A with eigenvectors $v_1, ..., v_k$ where $v_j = r_j + is_j$. Then the 2k **real** valued linearly independent solutions to x' = Ax are:

$$e^{at}(\cos(bt)r_1+\sin(bt)s_1), e^{at}(\cos(bt)r_2+\sin(bt)s_2), ..., e^{at}(\cos(bt)r_k+\sin(bt)s_2))$$

and

$$e^{at}(\cos(bt)r_1 - \sin(bt)s_1), e^{at}(\cos(bt)r_2 - \sin(bt)s_2), ..., e^{at}(\cos(bt)r_k - \sin(bt)s_2)$$