Determinants. Transpose. A
$$\leftrightarrow$$
 a $_{i\,j}$
$$\mathbf{A}^{T} \leftrightarrow \mathbf{a}_{i\,i}$$

$$Det(A) = Det(A^T)$$

Row operation ←→ Column operations

- 1. Exchange two columns multiplies determinant by -1
- 2. Multiply a column by s multiplies determinant by s.
- 3. Replace a column by itself plus a multiple of another column leaves the determinant unchanged.

Cofactor $C_{ij}=\det$ (A with i^{th} row and j^{th} column crossed off). Signed cofactor = $(-1)^{i+j}C_{ij}$

$$(A^{-1})_{ij} = (-1)^{i+j} C_{ij}^T / Det(A) = (-1)^{i+j} C_{ji} / Det(A)$$

$$Det(A) = \sum_{k=1}^{n} a_{ki} (-1)^{i+j} C_{ki} = \sum_{k=1}^{n} a_{ik} (-1)^{i+j} C_{ik}$$

e.g. 3×3 matrix.

$$Det(A) = a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) + a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

Last time. A vector space V

Form linear combinations. $s\overline{u} + \overline{v}$ zero vector $\overline{0}$ $\overline{u} + \overline{0} = \overline{u}$ $\overline{u} - \overline{u} = \overline{0}$ 0 $\overline{u} = \overline{0}$

If $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ is a set of vectors we say \overrightarrow{u} is a linear combination of these vectors if $\overrightarrow{u} = s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \cdots + s_n \overrightarrow{v_n}$

A subspace S of a vector space V is a subset of V which is also a vector space (i.e. if \overrightarrow{u} , \overrightarrow{v}) \in S then $a\overrightarrow{u}$ + $b\overrightarrow{v}$ \in S for all real numbers a and b. Note the set S consisting of one point $\overrightarrow{0}$ is a subspace of V. Note V itself is a subspace of V.

If $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \dots, \overrightarrow{v_n}\} \in V$ (a vector space) we denote by the Span $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \dots, \overrightarrow{v_n}\}$ the set of vectors which are linear combintations of the \overrightarrow{v} 's. Note span of a set of vectors is a linear subspace.

$$\overrightarrow{u} = s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \cdots + s_n \overrightarrow{v_n}$$

$$\overrightarrow{w} = r_1 \overrightarrow{v_1} + r_2 \overrightarrow{v_2} + \cdots + r_n \overrightarrow{v_n}$$

$$a\overrightarrow{u} + b\overrightarrow{v} = (as_1 + br_1) \overrightarrow{v_1} + (as_2 + br_2) \overrightarrow{v_2} + \cdots + (as_n + br_n) \overrightarrow{v_n}$$

A set of vectors $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ are linearly independent if $s_1\overrightarrow{v_1} + s_2\overrightarrow{v_2} + \cdots + s_n\overrightarrow{v_n} = 0$ then $s_1 = s_2 = \cdots = s_n = 0$.

A set of vectors $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ are linearly independent if each vector $\overrightarrow{v_j}$ is not a linear combination of the remaining $\overrightarrow{v_k}$.

A basis for a vector space V is a set linearly independent set of vectors $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ so that the span of these vectors is all of V (i.e. every vector $\overrightarrow{u} \in V$ is a linear combination of the \overrightarrow{v} 's i.e. $\overrightarrow{u} = s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \cdots + s_n \overrightarrow{v_n}$.

A basis for a vector space is a maximal linearly independent set of vectors $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \dots, \overrightarrow{v_n}\}$ in that you can not add a vector to the set and have a linearly independent set of vectors. If you add a vector \overrightarrow{u} to the set then

$$-1\overline{u}$$
 + $s_1\overline{v_1}$ + $s_2\overline{v_2}$ + \cdots + $s_n\overline{v_n}$ = 0

Theorem. If V is a vector space and $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ is a basis for V and $\{\overrightarrow{u_1}, \overrightarrow{u_2}, \cdots, \overrightarrow{u_m}\}$ is a basis for V then n = m.

Proof. I remember Professor Towne at Amherst explaining this.

The proof is complicated and to understand it you have to sit down and go through it for yourself. I will just give you the ideas.

Start of with

Then
$$\overrightarrow{u_1} = s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \cdots + s_n \overrightarrow{v_n}$$

 $\label{eq:Note all the s's are zero.} \ \ \mbox{Let s_k be the one of the non zero $s's.}$

$$\overrightarrow{v_k} = s_k^{-1} (\overrightarrow{u_1} - s_1 \overrightarrow{v_1} + s_2 \overrightarrow{v_2} + \cdots + s_{k-1} \overrightarrow{v_{k-1}} + s_{k+1} \overrightarrow{v_{k+1}} + \cdots + s_n \overrightarrow{v_n})$$

So

$$\{\overline{v_1}, \overline{v_2}, \dots, \overline{v_{k-1}}, \overline{v_{k+1}}, \dots, \overline{v_n}, \overline{u_1}\}$$
 is a basis.

Now add $\overrightarrow{u_2}$ and cross off another \overrightarrow{v}

Keep going. Until you run out of \overrightarrow{v} 's

You can't run out of \overline{u} 's because if you did the \overline{u} 's would not have been a basis. Hence, $n \le m$. But repeat the proof with stating with the \overline{u} 's and cross off \overline{v} 's. You conclude $m \le n$. Hence, n = m.

How to compute the dimension of a subspace span $\{\overrightarrow{v_1}, \overrightarrow{v_2}, \cdots, \overrightarrow{v_n}\}$ Write the vectors as rows

$$v_1 \quad v_2 \qquad v_n \\ v_1 \quad v_2 \qquad v_n \\ v_1 \quad v_2 \qquad v_n \\ v_1 \quad v_2 \qquad v_n$$

row reduce.

Number of rows after row reduction.

Want a basis for the subspace. Take the rows after row reduction.