

DIRECTIONS This exam has two parts, the first has four short computations (5 points each) while the second has seven traditional problems (10 points each).

Part A: Short Computations (4 problems, 5 points each)

A-1. Find a real 2×2 matrix A (other than $A = \pm I$) such that $A^4 = I$.

Solution Two solutions are $A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ (reflection across the x -axis and $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ (reflection across the line $y = x$). Both of these satisfy $A^2 = I$ so clearly $A^4 = I$.

A more interesting example that does *not* satisfy $A^2 = I$ is $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ (rotation by 90 degrees).

A-2. Find a function $u(x, y)$ satisfying $\frac{\partial u}{\partial x} - 2u = 0$ with $u(0, y) = \sin(3y)$.

Solution This is just the ODE $u' - 2u = 0$ with y as a parameter. The general solution (say using separation of variables) is $u(x, y) = C(y)e^{2x}$. But $\sin(3y) = u(0, y) = C(y)$. Thus

$$\boxed{u(x, y) = \sin(3y)e^{2x}}.$$

A-3. Say $T(x, y, z) = x^2 + xy + y^3 - z^2$ gives the temperature at the point (x, y, z) . At the point $(1, 1, 1)$, in which direction should one move so that the temperature increases fastest?

Solution The gradient of a function is a vector pointing in the direction where the function increases most rapidly. Since

$$\nabla f(x, y, z) = (2x + y, x + 3y^2, -2z),$$

the desired direction at $(1, 1, 1)$ is $(3, 4, -2)$. If you prefer, you can use a unit vector in this direction.

A-4. Compute $J := \iint_{\mathbb{R}^2} \frac{1}{[1 + (2x + y + 1)^2 + (x - y + 3)^2]^2} dx dy$.

Solution Make the change of variables

$$u = 2x + y + 1, \quad v = x - y + 3.$$

Then

$$du dv = \left| \det \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} \right| dx dy = 3 dx dy$$

so $dx dy = \frac{1}{3} du dv$. Thus

$$J = \frac{1}{3} \iint_{\mathbb{R}^2} \frac{1}{[1 + u^2 + v^2]^2} du dv,$$

which is computed using polar coordinates in the uv plane

$$J = \frac{1}{3} \int_0^{2\pi} \left[\int_0^\infty \frac{1}{[1 + r^2]^2} r dr \right] d\theta = \frac{\pi}{3}.$$

Part B: Traditional Problems (7 problems, 10 points each)

B-1. If $A = \begin{pmatrix} 1 & 4 \\ 4 & 1 \end{pmatrix}$, find an invertible matrix C such that $D := C^{-1}AC$ is a diagonal matrix. Compute A^{50} .

Solution This is routine. D has the eigenvalues of A and the columns of C are the corresponding eigenvectors of A . Since A is a symmetric matrix, by using unit eigenvectors we even have that C is an orthogonal matrix (so its inverse is easier to compute). The upshot is

$$\lambda_1 = 5, \quad \lambda_2 = -3, \quad v_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad v_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

so

$$D = \begin{pmatrix} 5 & 0 \\ 0 & -3 \end{pmatrix} \quad C = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad .$$

To compute A^{50} , use $A = CDC^{-1}$ to find

$$A^{50} = CD^{50}C^{-1} = \frac{1}{2} \begin{pmatrix} 5^{50} + (-3)^{50} & 5^{50} - (-3)^{50} \\ 5^{50} - (-3)^{50} & 5^{50} + (-3)^{50} \end{pmatrix}.$$

B-2. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^k$ be a real matrix (not necessarily square). If the nullspace of T is $\{0\}$, show that the matrix T^*T is invertible and positive definite.

Solution First we show that T^*T is positive definite. For any vector $x \in \mathbb{R}^n$

$$\langle x, T^*Tx \rangle = \langle Tx, TX \rangle = \|Tx\|^2 \geq 0.$$

This also shows that $\langle x, T^*Tx \rangle = 0$ only when $Tx = 0$. Since the nullspace of T is $\{0\}$, this occurs only when $x = 0$, so T^*T is positive definite.

The above computation contains the proof that the nullspace of the square matrix T^*T is $\{0\}$; thus it is invertible.

B-3. Let a_n be a bounded sequence of real numbers. If $c > 1$, show that the series $\sum \frac{a_n}{n^x}$ converges uniformly in the region $x \geq c$.

Solution Say $|a_n| \leq M$. If $x \geq c > 1$, then

$$\left| \sum \frac{a_n}{n^x} \right| \leq M \sum \frac{1}{n^c}.$$

Because $c > 1$, this last series converges so by the Weierstrass M-Test, the original series converges uniformly for $x \geq c > 1$.

B-4. Let $\gamma(t)$ define a smooth curve that does not pass through the origin. If the point $\mathbf{P} = \gamma(t_0)$ is a point on the curve that is closest to the origin (and *not* an end point of the curve), show that the position vector $\gamma(t_0)$ is perpendicular to the tangent vector $\gamma'(t_0)$.

Solution At t_0 the function $h(t) := \|\gamma(t)\|^2 = \langle \gamma(t), \gamma(t) \rangle$ has a local minimum. Thus

$$0 = h'(t_0) = 2\langle \gamma(t_0), \gamma'(t_0) \rangle,$$

so $\gamma(t_0)$ is orthogonal to $\gamma'(t_0)$. Now observe that $\gamma'(t_0)$ is just the tangent vector at t_0 .

B-5. Let A be an $n \times n$ real symmetric matrix with eigenvalues $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$ and corresponding orthonormal eigenvectors v_1, \dots, v_n . Show that

$$\lambda_2 = \min_{x \neq 0, x \perp v_1} \frac{\langle x, Ax \rangle}{\|x\|^2}.$$

Solution Since the eigenvectors form an orthonormal basis, we can write $x = x_1 v_1 + \dots + x_n v_n$ for some x_j . Then $\langle x, Ax \rangle = \lambda_1 x_1^2 + \lambda_2 x_2^2 + \dots + \lambda_n x_n^2$. Now $x \perp v_1$ implies that $x_1 = 0$. Since $\lambda_2 \leq \dots \leq \lambda_n$ we find

$$\langle x, Ax \rangle \geq \lambda_2(x_2^2 + \dots + x_n^2) = \lambda_2 \|x\|^2.$$

Equality occurs if $x = v_2$.

B-6. Let $f(x)$ be a continuous function for $0 \leq x \leq 1$. Compute $J_n(f) := \lim_{n \rightarrow \infty} n \int_0^1 f(x) e^{-3nx} dx$.

Solution Observe that if $x \geq \delta > 0$, then $ne^{-3nx} \leq ne^{-2n\delta} \rightarrow 0$, while at $x = 0$ the function $ne^{-3nx} = n$ blows-up. Thus all the action occurs at $x = 0$.

METHOD 1: Write

$$\begin{aligned} J_n(f) &= n \int_0^1 [f(x) - f(0)] e^{-3nx} dx + n \int_0^1 f(0) e^{-3nx} dx \\ &= n \int_0^1 [f(x) - f(0)] e^{-3nx} dx + \frac{1}{3} f(0). \end{aligned}$$

I show that for n large the first integral in the above line can be made arbitrarily small. Given $\epsilon > 0$, pick δ do that if $0 \leq x < \delta$ then $|f(x) - f(0)| < \epsilon$. Also, say $|f(x)| \leq M$ for $0 \leq x \leq 1$. Then

$$\begin{aligned} n \int_0^1 [f(x) - f(0)] e^{-3nx} dx &\leq \int_0^\delta + \int_\delta^1 \\ &\leq \epsilon n \int_0^\delta e^{-3nx} dx + 2Mn \int_\delta^1 e^{-3nx} dx \leq \frac{1}{3} \epsilon + \frac{1}{3} 2M e^{-3n\delta}. \end{aligned}$$

Now let $n \rightarrow \infty$

METHOD 2: If f is smooth you can integrate by parts to compute the limit. More precisely, if $h \in C^1[0, 1]$ then

$$\begin{aligned} J_n(h) &= -\frac{1}{3} h(x) e^{-3nx} \Big|_0^1 + \frac{1}{3} \int_0^1 h'(x) e^{-3nx} dx \\ &= \frac{1}{3} \left[-h(1) e^{-3n} + h(0) + \int_0^1 h'(x) e^{-3nx} dx \right]. \end{aligned}$$

Because $h \in C^1[0, 1]$, h' is bounded: $|h'| \leq M$. Therefore $\left| \int_0^1 h'(x)e^{-3nx} dx \right| < M/3n$. Consequently

$$|J_n(h) - \frac{1}{3}h(0)| < \frac{1}{3} \left[-h(1)e^{-3n} + \frac{M}{3n} \right] \rightarrow 0.$$

If f is only continuous, use the Weierstrass approximation theorem to find a smooth function h so that $|f(x) - h(x)| < \epsilon$ for all $x \in [0, 1]$. Then write

$$J_n(f) - \frac{1}{3}f(0) = J_n(f - h) + [J_n(h) - \frac{1}{3}h(0)] + \frac{1}{3}[h(0) - f(0)].$$

Since $|f(x) - h(x)| < \epsilon$, then $|J_n(f - h)| < \epsilon/3$ and $\frac{1}{3}[h(0) - f(0)] < \epsilon/3$. Letting $n \rightarrow \infty$ we also have $J_n(h) - \frac{1}{3}h(0) \rightarrow 0$. Thus $J_n(f) \rightarrow f(0)/3$.

B-7. Let \mathcal{D} be a bounded region in the plane, and \mathcal{B} be its boundary (assumed smooth). Let $u(x, y, t)$ be a solution of the heat equation $\frac{\partial u}{\partial t} = \Delta u$ for (x, y) in \mathcal{D} . Say that the temperature $u(x, y, t) = 0$ for all points (x, y) on the boundary \mathcal{B} .

If $E(t) := \frac{1}{2} \iint_{\mathcal{D}} u^2(x, y, t) dx dy$, show that $dE/dt \leq 0$.

Solution

$$\frac{dE}{dt} = \iint_{\mathcal{D}} uu_t dx dy = \iint_{\mathcal{D}} u\Delta u dx dy.$$

Now integrate by parts (the divergence theorem) to get

$$\iint_{\mathcal{D}} u\Delta u dx dy = \int_{\mathcal{B}} u\nabla u \cdot N ds - \iint_{\mathcal{D}} |\nabla u|^2 dx dy,$$

where N is the unit outer normal and ds is the element of arc length, respectively, on \mathcal{B} . Since $u = 0$ on the boundary, the integral over \mathcal{B} is zero so

$$\frac{dE}{dt} = - \iint_{\mathcal{D}} |\nabla u|^2 dx dy \leq 0.$$