

# Lecture 6 - F-structures I, Definitions

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*This lecture's reference is Cheeger-Gromov's 1986 JDG paper "Collapsing Riemannian manifold while keeping their curvature bounded. I."*

## 1 Definitions

**Def** A *partial action*,  $A$ , of a topological group  $G$  on a Hausdorff space  $X$  is given by

- i.* The *domain* of the action: a neighborhood  $\mathcal{D} \subset G \times X$  of  $\{e\} \times X$ .
- ii.* A continuous map  $A : \mathcal{D} \rightarrow X$ , also written  $(g, x) \rightarrow gx$ , such that  $(g_1g_2)x = g_1(g_2x)$  whenever  $(g_1g_2, x)$  and  $(g_1, g_2x)$  lie in  $\mathcal{D}$ .

To emphasize the domain, a partial action  $A$  can be written  $(A, \mathcal{D})$ . An equivalence relation exists on the set of partial actions; an equivalence class is called a *local action*. Two partial actions  $(A_1, \mathcal{D}_1)$  and  $(A_2, \mathcal{D}_2)$  of a topological group  $G$  on a Hausdorff space  $X$  are equivalent if for any open subset  $\mathcal{D} \subset \mathcal{D}_1 \cap \mathcal{D}_2$  with  $\{e\} \times X \subset \mathcal{D}_1 \cap \mathcal{D}_2$ , we have  $A_1|_{\mathcal{D}} = A_2|_{\mathcal{D}}$ ; an equivalence class is denoted by  $[A]$ . We list some additional facts and definitions.

- Any global action defines a local action; an equivalence class which has such a member will be called *complete*. Notice that if  $G$  is connected, any two global actions in the same equivalence class are identical.
- In the smooth category, the local actions of a Lie group  $G$  is in 1-1 correspondence with the homomorphisms from the Lie algebra of  $G$  to the Lie algebra of vector fields on  $X$ . The completeness of an action is the same as the *global* integrability of the individual vector fields.
- If  $[A]$  is a local action, a subset  $X_0 \subset X$  is called  $[A]$ -invariant if whenever  $x_0 \in X_0$  and  $(g, x_0) \in \mathcal{D}$  then  $gx_0 \in X_0$ . The intersection of  $[A]$ -invariant sets is  $[A]$ -invariant, so any point  $x$  lies in a minimal  $[A]$ -invariant set, called the orbit of  $x$ , denoted  $\mathcal{O}_x$  or just  $\mathcal{O}$ .

- The orbits of  $X$  form a partition.
- Unlike an action, a local action  $[A]$  on  $X$  pulls back along any local homeomorphism  $f : Y \rightarrow X$  to a local action  $f^*[A]$  on  $Y$ .
- A local action  $[A]$  on  $X$  can be restricted to any subset  $U \subset X$  by restricting the domain  $\mathcal{D}$  of any representative of  $[A]$  to any open subset  $\mathcal{D}'$  that contains  $\{e\} \times U$  and which obeys (ii) from above.
- If  $(A_1, \mathcal{D}_1)$  represents a local action on  $U_1$  and  $(A_2, \mathcal{D}_2)$  represents a local action on  $U_2$  and if  $A_1|_{U_1 \cap U_2} = A_2|_{U_1 \cap U_2}$ , a local action on  $U \cup V$  can be taken to be the equivalence class of the partial action  $(A_1|_{U_1 \cap U_2}, \mathcal{D}_1 \cap \mathcal{D}_2)$ . This equivalence class is uniquely defined.

The last two points suggest compatibility with another topological construction that is perhaps more familiar.

**Def** A *sheaf*  $\mathfrak{F}$  on a topological space  $X$  is an association between open sets  $U \subset X$  and groups that satisfies the following three axioms.

- $\mathfrak{F}(U)$  is a group whenever  $U$  is an open subset and  $\mathfrak{F}(\emptyset) = \{0\}$ , of  $X$
- If  $V \subseteq U$  is an inclusion of open sets, there is a homomorphism (the restriction, or structure homomorphism)  $\rho_{VU} : \mathfrak{F}(U) \rightarrow \mathfrak{F}(V)$  subject to the restrictions (i) that  $\rho_{UU} = \text{Id}$  and (ii) that  $W \subseteq V \subseteq U$  implies  $\rho_{WU} = \rho_{WV} \circ \rho_{VU}$ .
- If  $\{U_\alpha\}$  is an open covering of  $U$  and  $s_\alpha \in \mathfrak{F}(U_\alpha)$  satisfies  $s_\alpha|_{U_\alpha \cap U_\beta} = s_\beta|_{U_\alpha \cap U_\beta}$ , then there exists a unique element  $s \in \mathfrak{F}(U)$  so that  $s|_{U_\alpha} = s_\alpha$ .

If  $\mathfrak{F}$  only satisfies (a) and (b) it is called a *presheaf*. A salient feature of sheafs is the existence of a *stalk* over each point. Let  $\mathfrak{F}$  be a sheaf over  $M$ , and let  $p \in M$ . Let  $\{U_\alpha\}_{\alpha \in \mathcal{A}}$  be the family of open sets containing  $p$ . Then the  $\mathfrak{F}(U_\alpha)$  along with the structure homomorphisms constitute a directed family of groups, the direct limit of which is called the stalk at  $p$ . A topology can be put on the space of stalk: a neighborhood base is given by the images of the “sections”  $\mathfrak{F}(U)$  in the space of stalks. Stalks can be defined if just a presheaf structure exists, and then sections of the space of stalks constitute a sheaf (the *sheafification* of the presheaf).

Let  $\mathfrak{g}$  be a sheaf of connected topological groups (note there is some question about topology here; we just accept that there are two topologies, the sheaf topology, and a topology that makes the stalks into Lie groups— we usually ignore the sheaf topology). An *action* of  $\mathfrak{g}$  on  $X$  is given by a local action of  $\mathfrak{g}(U)$  for each open  $U$  such that the local actions agree with the sheaf restriction maps. To be explicit, when  $x \in V \subset U$  and  $g \in \mathfrak{g}(U)$ , we have  $gx = \rho_{VU}(g)x$  wherever  $\rho_{VU}(g)x$  is defined.

A set  $S \subset X$  is called invariant if  $S \cap U$  is invariant under  $\mathfrak{g}(U)$  for all open subsets  $U \subset X$ . A minimal invariant set is called an orbit. The orbits partition  $X$ , and a set that is the disjoint union of orbits is called *saturated*.

We use  $\mathfrak{g}_x$  to denote the stalk of  $\mathfrak{g}$  at  $x \in X$ . If  $f : X \rightarrow Y$  is a local homeomorphism then we denote by  $f^* \mathfrak{g}$  the pullback sheaf.

**Def** An action of a sheaf  $\mathfrak{g}$  is called a *complete local action* if

- i. Whenever  $x \in X$  there exists a neighborhood  $V(x)$  of  $x$  and a local homeomorphism  $\pi : \tilde{V}(x) \rightarrow V(x)$  so that  $\tilde{V}(x)$  is Hausdorff
- ii. If  $\tilde{x} \in \pi^{-1}(x)$  and  $\tilde{\mathfrak{g}}$  denotes the pullback of  $\mathfrak{g}$  along  $\pi$ , then for any open set  $\tilde{W} \subset \tilde{V}(x)$  with  $\tilde{x} \in \tilde{W}$ , the structure homomorphism  $\tilde{\mathfrak{g}}(\tilde{W}) \rightarrow \mathfrak{g}_{\tilde{x}}$  is an isomorphism
- iii. The local action of  $\tilde{\mathfrak{g}}(\tilde{V}(x))$  on  $\tilde{V}(x)$  is complete.

If  $\pi : \tilde{V}(x) \rightarrow V(x)$  is a covering space, the deck transformation group  $\Gamma$  induces a natural action on  $\pi^* \mathfrak{g}$ , called the *holonomy action*. Specifically, if  $g \in \mathfrak{g}(U)$  then  $\gamma(g)$  acts on elements  $x \in \gamma(U)$  via  $\gamma(g) = \gamma \circ g \circ \gamma^{-1}$ . One verifies that for  $\gamma \in \Gamma$ , we have  $\gamma(gx) = \gamma(g)\gamma(x)$ .

**Def** A  $\tilde{\mathfrak{g}}$ -structure  $\mathcal{G}$  on  $X$  is a sheaf,  $\mathfrak{g}$ , of connected topological groups and a complete local action of  $\mathfrak{g}$  on  $X$  such that the sets  $V(x)$  and  $\tilde{V}(x)$  can be chosen so that

- i.  $\pi : \tilde{V}(x) \rightarrow V(x)$  is a normal covering map
- ii. For all  $x$ ,  $V(x)$  is saturated
- iii. For all  $\mathcal{O}$ , if  $x, y \in \mathcal{O}$ , then  $V(x) = V(y)$ .

Condition (iii) implies that  $\mathfrak{g}$  is a locally constant sheaf on  $\overline{\mathcal{O}}$ , though not necessarily on neighborhoods of  $\overline{\mathcal{O}}$ .

**Def** A  $\tilde{\mathfrak{g}}$ -structure  $\mathcal{G}$  is called an F-structure if each stalk  $\mathfrak{g}_x$  is isomorphic to a torus, and the local covers  $\tilde{V}(x) \rightarrow V(x)$  can be chosen to be finite normal covers. If in addition one can choose  $\tilde{V}(x) = V(x)$ , then  $\mathcal{G}$  is called a *T-structure*.

## 2 Exercises

- 1) Consider the action of the Lie group  $G = (\mathbb{R}, +)$  on itself; this determines a complete local action  $[A_{\mathbb{R}}]$ . Let  $X = (a, b) \subset \mathbb{R}$ . It was claimed that the local action  $[A_{\mathbb{R}}]$  on  $\mathbb{R}$  restricts to a local action  $[A_X]$  on  $X$ . Give an example of a partial action  $A \in [A_X]$  by specifying the domain and the action.
- 2) In the context of the previous example, let  $X = (0, 2)$  and  $Y = (1, 3)$ , and let  $(A_X, \mathcal{D}_X)$  and  $(A_Y, \mathcal{D}_Y)$  be partial actions on  $X$  and  $Y$ , respectively. To make this example explicit, write down explicit choices for the domains  $\mathcal{D}_X$  and  $\mathcal{D}_Y$ . Given these choices, describe the consequent partial action on  $Z = (0, 3)$  with  $\mathcal{D}_Z = \mathcal{D}_X \cap \mathcal{D}_Y$ .

- 3) Let  $f : \tilde{X} \rightarrow X$  be a local homeomorphism between the Hausdorff spaces  $\tilde{X}$  and  $X$ . Prove that any local action on  $X$  lifts to a partial action on  $\tilde{X}$ .
- 4) There is an obvious partial action of  $\mathbb{S}^1$  on itself, which is also an action. Since  $\mathbb{R} \rightarrow \mathbb{S}^1$  is a covering map and therefore a local homeomorphism, there is a local action of  $\mathbb{S}^1$  on  $\mathbb{R}$ . Give a description of some partial action in this local action.
- 5) The local action of  $\mathbb{S}^1$  on  $\mathbb{R}$  described in the previous exercise can easily be made into the local action of a sheaf of groups over  $\mathbb{R}$ , with stalk  $\mathbb{S}^1$  at each point (a constant sheaf). Prove that this local action is *not* a complete local action.