## Symplectic Geometry and Geometric Quantization

#### Samuel Goldstein

Mentor: Christopher Bailey

December 10, 2020

### Definition:

In classical mechanics the **phase space** is the set of all possible states of a system. For a mechanical system, the phase space consists of pairs  $(\vec{q}, \vec{p})$  of generalized coordinates  $(\vec{q})$  and generalized momenta  $(\vec{p})$ 

Some Remarks:

- The set of all positions is called the configuration space of the system
- *Example:* The phase space of an unconstrained particle in moving in 3 dimensions can be represented by  $(\vec{q}, \vec{p}) \in \mathbb{R}^3 \times \mathbb{R}^3 \sim \mathbb{R}^6$

### Definition:

A **Hamiltonian** is a smooth function on the phase space:  $\mathcal{H}: \mathcal{P} \to \mathbb{R}$ 

• The Hamiltonian encodes the total energy of a system

### Definition:

Given a Hamiltonian  $\mathcal{H}$ , the time evolution of a system in phase space is determined by solutions to **Hamilton's Equations:** 

$$\dot{q}_i(t)=rac{\partial \mathcal{H}}{\partial 
ho_i}(ec{q},ec{
ho}) ext{ and } \dot{
ho}_i(t)=-rac{\partial \mathcal{H}}{\partial q_i}(ec{q},ec{
ho})$$

ullet Can prove Newton's Laws  $\iff$  Hamilton's equations are satisfied

### Definition:

Given two smooth functions  $F, G : M \to \mathbb{R}$  on the phase space, the **Poisson bracket** gives a third function  $\{F, G\} = \sum_{i=1}^{N} \left( \frac{\partial F}{\partial q_i} \frac{\partial G}{\partial p_i} - \frac{\partial F}{\partial p_i} \frac{\partial G}{\partial q_i} \right)$ 

• For any function  $F(\vec{q}(t), \vec{p}(t), t)$  on the phase space, the Poisson bracket can be used to compute its time derivative:  $\frac{dF}{dt} = \{F, \mathcal{H}\} + \frac{\partial F}{\partial t}$ 

#### Definition:

A symplectic manifold is a 2n dimensional smooth manifold M equipped with a two-form  $\omega$  called the symplectic form which has the following properties:

- $\omega$  is closed:  $d\omega = 0$
- $\omega$  is non-degenerate: if  $\omega_p(v, w) = 0$  for all  $v \in T_p M$ , then  $w = \vec{0}$ .

The following theorem suggests that *all* symplectic manifolds of the same dimension are locally the same

#### Darboux's Theorem:

Let  $(M, \omega)$  be a 2n dimensional symplectic manifold. For every  $p \in U \subset M$  there exists a chart  $(U, x_1, ..., x_n, y_1, ..., y_n)$  about p such that  $\omega = \sum_{j=1}^n dx_i \wedge dy_j$ 

### Symplectic Manifolds are the Natural Setting for Classical Mechanics

- Configuration space can often be represented by a smooth manifold  ${\it M}$
- Phase space represented by the cotangent bundle of *M*:

$$\mathcal{T}^* \mathcal{M} \coloneqq \{(q,p) \mid q \in \mathcal{M}, \; p \in \mathcal{T}^*_q \mathcal{M}\}$$

 Natural symplectic structure on *T*<sup>\*</sup>*M* with ω := dq ∧ dp which determines the Poisson Bracket {*H*, *K*} = ω(X<sub>H</sub>, X<sub>K</sub>)

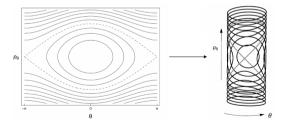


Figure: Phase space of simple pendulum is a cylinder. The configuration space is  $M = S^1$  which has trivial cotangent bundle, hence  $T^*M = S^1 \times \mathbb{R} \simeq C$ 

### Classical vs. Quantum Mechanics

- Can we use symplectic geometry to understand quantum mechanics?
  - Quantum mechanical states cannot have definite position and momenta  $(\Delta x \cdot \Delta p \geq \frac{\hbar}{2})$

### **Classical Mechanics**

- Set of states given by a *symplectic* manifold M
- Time evolution determined by a Hamiltonian  $\mathcal{H}: M \to \mathbb{R}$  and Hamilton's equations

### Quantum Mechanics

- Set of states is given by a *Hilbert* Space V
- Time evolution is determined by a linear operator  $\hat{H}: V \to V$  and the Schrödinger Equation

Geometric Quantization

### Kähler Manifolds and Hermitian Line Bundles

Kähler Manifolds provide the underlying structure for generalizing a classical phase space into a Hilbert space

### Definition:

A Kähler manifold is a manifold with three mutually compatible structures:

- **(1)** a symplectic structure  $\omega$
- ② a complex structure  $J : T_p M \to T_p M$  (analogous to 90° rotation from multiplication by *i* ∈ ℂ)
- a Riemannian metric g

such that:  $\omega(v, Jw) = g(v, w)$  for all  $v, w \in T_pM$ .

- To geometrically quantize M need a Hermitian line bundle, L, over M with curvature  $i\omega$ 
  - Set of all holmorphic sections of L forms a Hilbert space

 Phase space of classical spin-j particle is surface of sphere of radius j parametrized by angles (θ, φ) with elements representing possible angular momenta vectors:

$$\vec{j} \coloneqq (j_x, j_y, j_z) = (j \sin \theta \cos \phi, j \sin \theta \sin \phi, j \cos \theta)$$

• Requiring the Poisson Bracket  $\{j_k, j_l\} = \epsilon_{kl}^m j_m$  yields the unique symplectic form:

$$\omega = j\sin\theta d\theta \wedge d\phi = d\phi \wedge d(j\cos\theta) \coloneqq dq \wedge dp$$

- How to construct Kähler manifold from  $(M, \omega)$ ?
  - Riemannian Structure: standard metric on a sphere of radius  $\sqrt{j}$
  - Complex Structure: to get Kähler manifold the real and imaginary parts must correspond to  $\omega$  and g, respectively
    - This is just the Riemann sphere  $M = \mathbb{C}P^1 \sim \mathcal{S}^2$  of radius  $\sqrt{j}$

- How to equip  $M = \mathbb{C}P^1$  with Hermitian L line bundle with curvature  $i\omega$ 
  - From algebraic topology, specifically characteristic (Chern) classes, this exists iff.  $\int_M \omega \in 2\pi\mathbb{Z}$

$$\int_{M} \omega = \int_{\mathcal{S}^2} j \sin \theta d\theta \wedge d\phi = \int_{0}^{2\pi} \int_{0}^{\pi} j \sin \theta d\theta d\phi = 4\pi j \in 2\pi \mathbb{Z} \iff j \in \frac{1}{2} \mathbb{Z}$$

• Desired line bundle exists only for half integer values  $j = 0, \frac{1}{2}, 1, ...$ 

- Holomorphic sections of L?
  - Sections about  $z = 0 \in \mathbb{C}P^1$  are given by  $\mathcal{F} = \{1, z, z^2, ..., z^N, ...\}$
  - $\implies$  Sections about  $z = \infty \in \mathbb{C}P^1$  are given by  $\mathcal{G} = \{z^{-2j}, z^{-2j+1}, ..., z^{-2j+N}, ...\}$
  - For  $\mathcal{F},\mathcal{G}$  to be regular at 0 and  $\infty,$  respectively we need  $N\leq -2j$
  - Hilbert space, V, corresponds to 2j + 1 dimensional complex vector space

# The Spin- $\frac{1}{2}$ Particle

- How to quantize spin- $\frac{1}{2}$  particle?
  - $j = \frac{1}{2} \implies 2j + 1 = 2$ , hence we expect dim (V) = 2
  - Formally, L is the dual of tautological line bundle on  $M = \mathbb{C}P^1$
  - Sections are linear functionals  $f:\mathbb{C}^2 \to \mathbb{C}$
  - $\bullet \implies V = \mathbb{C}^{2*} \simeq \mathbb{C}^2$
- Is  $\mathbb{C}^2$  the anticipated Hilbert space?
  - From QM, arbitrary spin- $\frac{1}{2}$  particle is in state  $|\psi\rangle = \alpha |0\rangle + \beta |1\rangle$ , with  $\alpha, \beta \in \mathbb{C}$
  - $\implies \mathbb{C}^2$  is the Hilbert space we expect to describe spin- $\frac{1}{2}$  degree of freedom

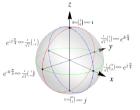


Figure: Quantum mechanical states of a spin- $\frac{1}{2}$  particle visualized using Bloch sphere

- Symplectic geometry is the natural setting for studying classical mechanics
  - Classical phase spaces are symplectic manifolds
- Recasting classical mechanics using symplectic geometry establishes parallels with quantum mechanics
- Geometric Quantization: Symplectic Manifold 
  Hilbert Space
  - Geometric quantization provides insights into quantum phenomena, such as spin

- Harvard Notes on Classical Mechanics and Symplectic Geometry
- Ø Berkeley Notes on Quantizing Spin
- John Baez's Notes on Geometric Quantization